

A055

Blind Analog Transmitter Instructions



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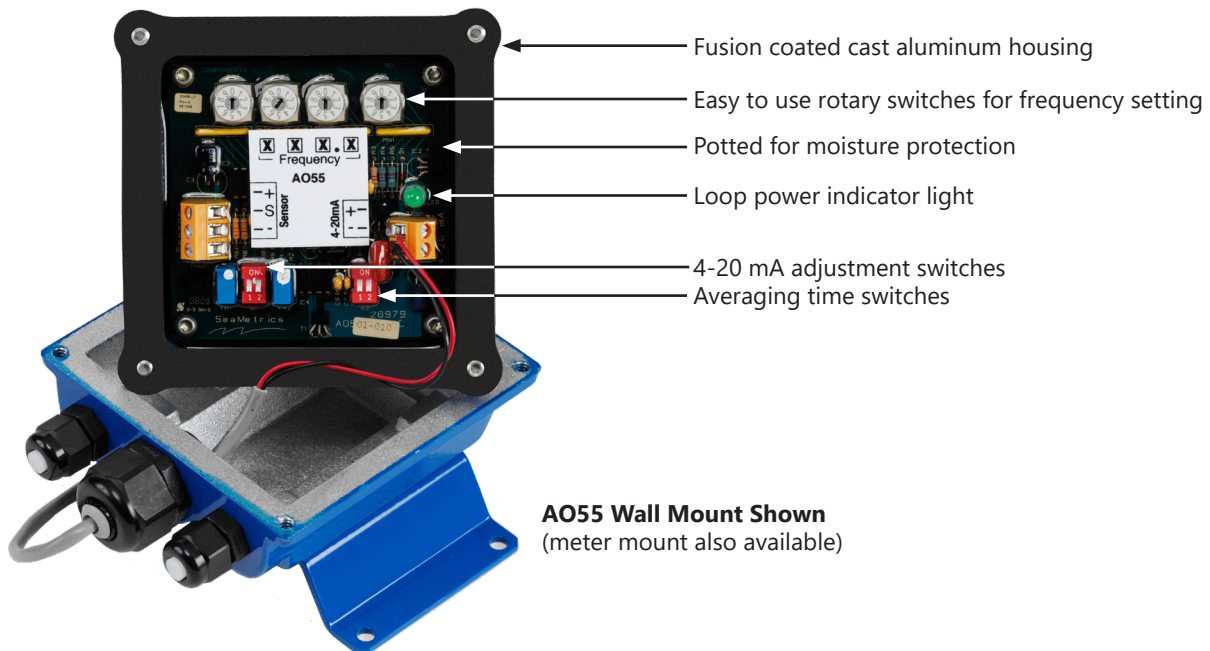
The Seametrics **AO55** is a blind (non-indicating) 4-20 mA transmitter, designed for use with almost all Seametrics flow sensors. It accepts a pulse frequency input from the flow sensor, and converts this input into a continuous analog output signal. Power for the transmitter is taken from the current loop itself, so only two wires are required. The digital design makes it possible to span the unit in the field without tools. The frequency at which 20 mA is desired is entered on a set of rotary switches, and an internal microcontroller automatically scales all other values accordingly. An additional benefit of the microcontroller is its ability to average inputs, for smoothing of the output signal. The degree of averaging can be selected in the field, from 2 to 16 seconds.

For maximum environmental protection, the electronic components are encased in a special semi-flexible urethane potting material. The housing is cast from aluminum and fuse-coated. The clamshell housing is connected directly to the flow sensor or, in the wall mount version, provided with mounting feet.

The AO55 will operate on a relatively wide range of current loop voltages, 24 to 36 Vdc. Lower voltages limit the load that can be applied to the loop without distortion of the signal. (See Load/Supply chart if there is a question regarding voltage vs. load.) A built-in power regulator supplies the appropriate power to the flow sensor.

Typical applications for this transmitter are telemetry (or SCADA), distributed control systems, programmable controllers, data logging, and chart recording.

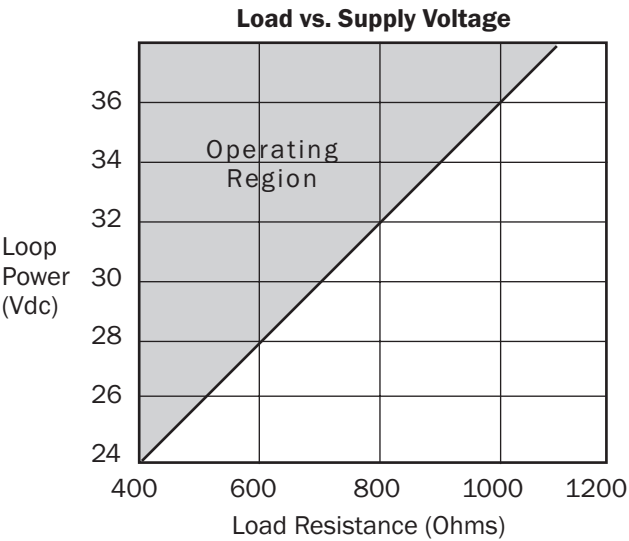
Features



Specifications *

Power		24–36 Vdc
Temperature		32° to 130° F (0° to 55° C)
Input		Open collector solid state sensor
Input Averaging		2–16 seconds (switch selectable)
Response Time		2–60 seconds; 90% of full scale (dependent on input averaging)
Frequency	Minimum	10 Hz (@20mA)
	Maximum	999.9 Hz
	Setting	4 Rotary DIP switches
Output		Proportional 4-20 mA
Environmental		NEMA 4X, IP66

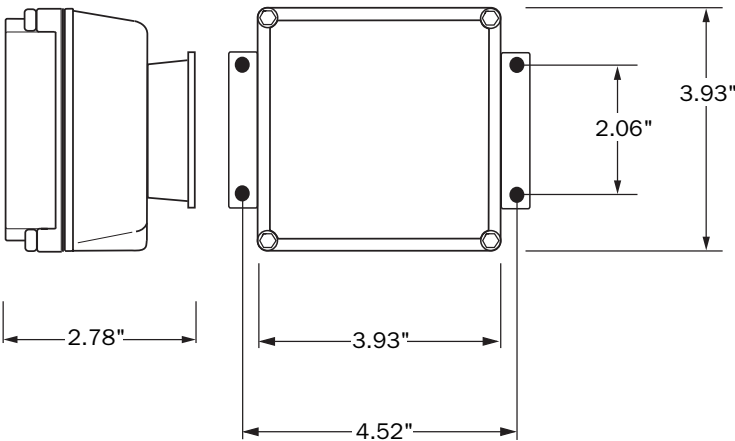
**Specifications subject to change.
Please consult our website for the most current data (www.seametrics.com).*



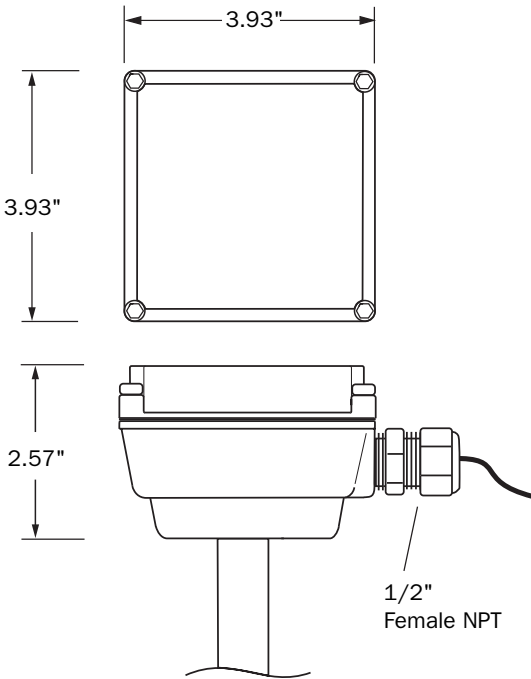
When calculating total resistive load for loop power (volts/.020 amps = ohms) be sure to subtract 800 Ω from the total to account for basic operation of the AO55

Dimensions

AO55 (Wall Mount)



AO55 (Meter Mount)



Mounting

The AO55M can be mounted on the flow sensor, or if wall mounted comes with mounting feet and requires four screws to attach it to any stable surface.

Connection

On either style of housing, the upper portion must be removed to make connections. Use a standard hex wrench (5/32" or 4 mm) to loosen the screws, then remove the upper half. The connections are made to terminal blocks in the upper half, which contains the potted electronics.

Consult the Connections diagram before connecting to the current loop. The only connections required on a meter mounted AO55 are the positive and negative loop connections. If wall mounted, the sensor must also be connected, since it is remote from the transmitter. Be careful to follow the color coding of the flow sensor wires in order to establish the correct polarity. Incorrect polarity can damage the sensor.

Setting Frequency

The AO55 converts a train of off/on pulses from the flow sensor into a continuous milliAmp signal that ranges from 4 mA at zero flow to 20 mA at the desired maximum flow. The desired maximum is determined by the user and entered as a frequency as follows:

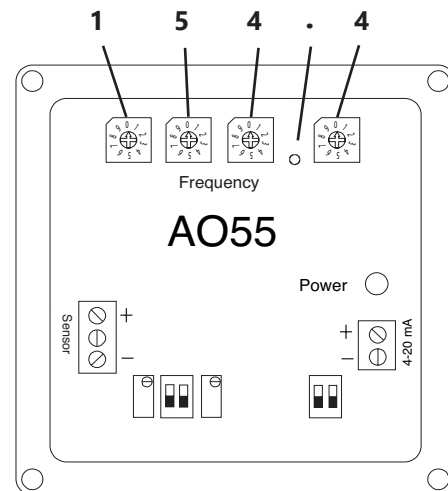
1. Decide what flow rate should represent the top of the scale. This is ordinarily the maximum expected flow, or a value just above it, in gallons per minute.
2. Locate the K-factor of the flow sensor (found on the meter or fitting, or in the instruction manual, depending on meter model). The K-factor is the number of pulses the flow sensor produces per gallon of flow.
3. Calculate frequency, using this formula:

$$\text{K-Factor} \times \frac{\text{Top Flow (GPM)}}{60} = \text{Frequency}$$
4. Enter the frequency using the four rotary Frequency switches. Note the decimal point between the third and fourth switches.

Example for Setting Frequency

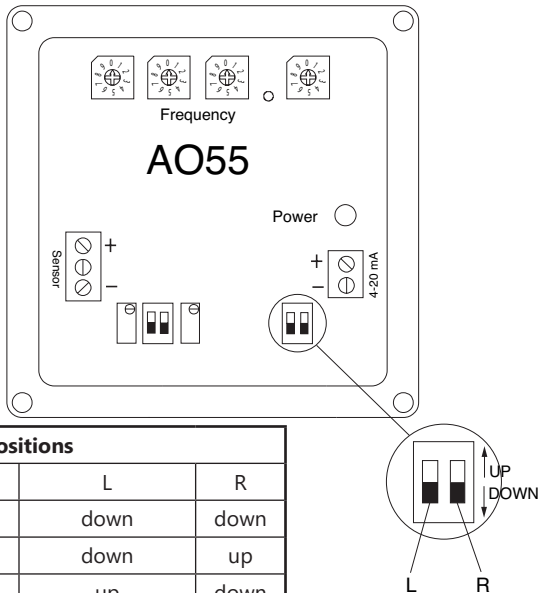
1. In an installation with an estimated maximum flow rate of about 150 GPM, a flow rate of 170 GPM is selected as the full-scale maximum, the flow at which the current loop will register 20 mA.
2. In this example, the K-factor (found on the meter or fitting, or in the manual) is "K = 54.50".
3. Calculate the frequency as:

$$54.50 \times \frac{170}{60} = 154.42$$
4. Rounding to one decimal point, enter 154.4 on the rotary switches by turning the rotary switch pointers to the desired digits.



Setting Averaging Time

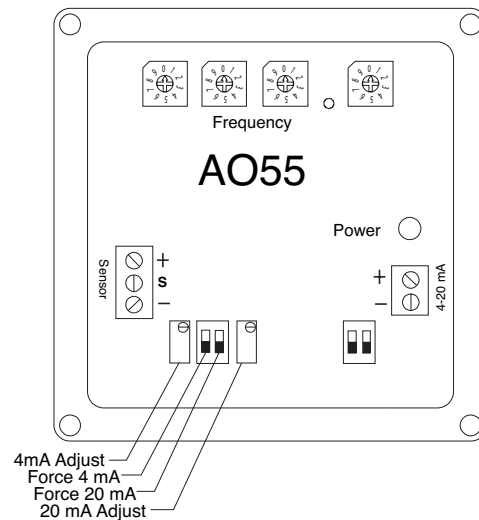
For most applications, this step can be ignored, as the standard setting will work fine. However, when a particularly steady output signal is desired, or in large pipe, a larger averaging period may be desirable. Note however that the averaging period requires a tradeoff, since a longer averaging period implies a slower response time. If steady signal is more important than fast response, increase the averaging time as desired. See the diagram below for the switch positions and their corresponding times.



Switch Positions		
Seconds	L	R
2	down	down
4	down	up
8	up	down
16	up	up

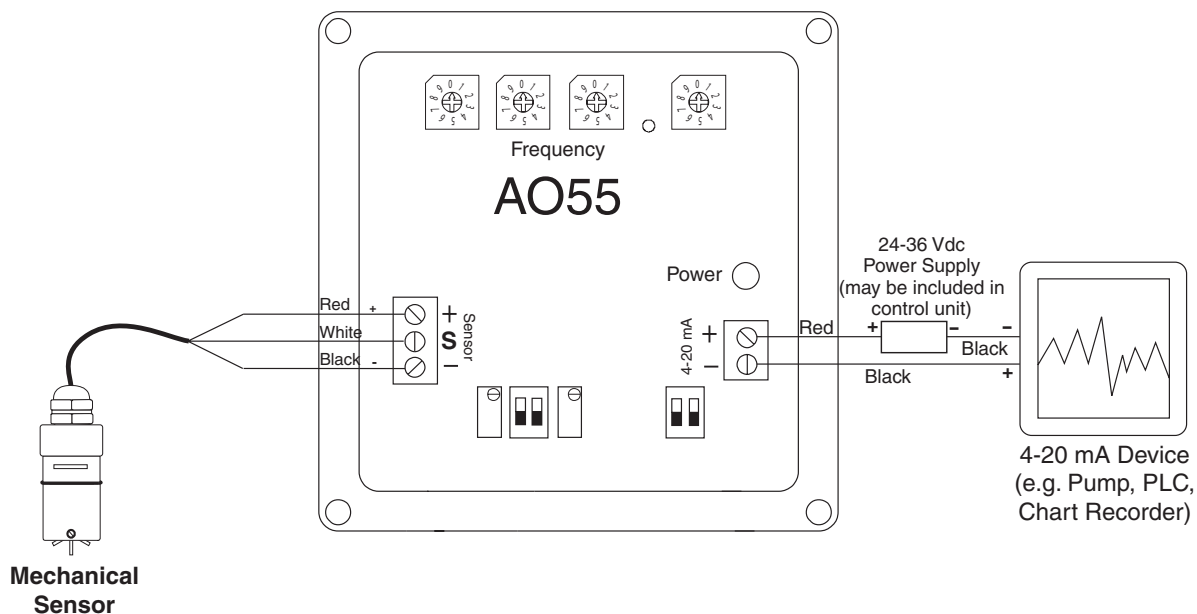
Checking Calibration

Normally it should not be necessary to check calibration, since the digital design of this unit virtually eliminates drift. However, there are two types of calibration check that can be performed. Look at the diagram below to locate the 4 and 20 mA force switches. To force the 4 mA output, put its switch in the up position. Check the current output at the Power terminals, and if necessary trim to 4.00 mA using the appropriate trimpot. Return the switch to the down position, and repeat the process with the 20 mA switch.

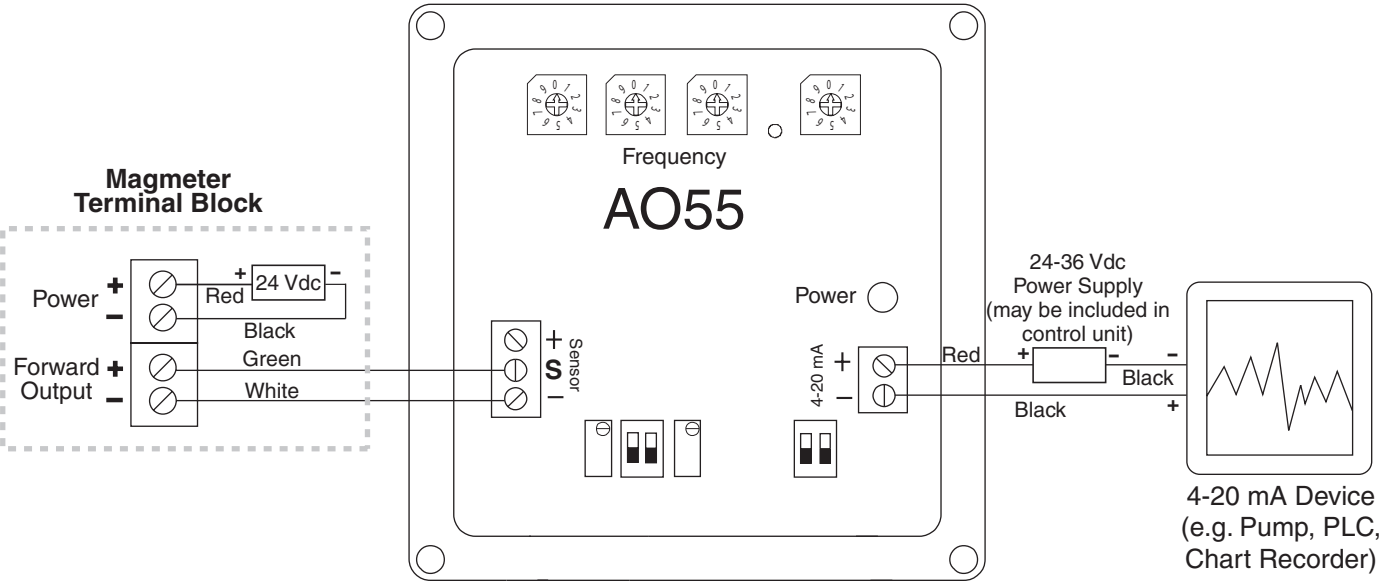


Wiring AO55 to a Mechanical Meter

The AO55 can be wired to either a mechanical meter or a magmeter. See configurations below.



Wiring AO55 to an EX Magmeter



Troubleshooting

Problem	Probable Causes	Things to try...
No analog signal at reading device	Break in current loop Dead power supply Reversed polarity	Check if loop indicator light is on Check multimeter voltage on power supply Check polarity
Output stuck at 4 mA	No frequency input from flow sensor	Check if flow sensor rotor is turning freely (mechanical meters only) Check flow sensor connections Check flow sensor polarity Be sure terminal blocks are firmly plugged in With flow sensor disconnected, use short wire to repeatedly short between sensor "sig" and "-" terminals. Output should rise. Verify 3-second pulse output (EX meters only)
mA signal does not match flow rate	Inadequate voltage Wrong frequency setting	Check load vs. supply chart Check multimeter voltage on power supply Review setting procedure

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Seametrics warrants that products manufactured by Seametrics, when delivered to you in new condition in their original containers and properly installed, shall be free from defects in material and workmanship. **Seametrics products are warranted against defects for a period of two (2) years from date of installation, with proof of install date. If no proof of install date can be provided, warranty period will be two (2) years from date of shipment from Seametrics, as defined on Seametrics' invoice.** Seametrics' obligation under this warranty shall be limited to replacing or repairing the part or parts, or, at Seametrics' option, the products, which prove defective in material or workmanship. The following are the terms of Seametrics' limited warranty:

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- b. Any defective part or parts must be returned to Seametrics' factory or to an authorized service center for inspection.
- c. Buyer will prepay all freight charges to return any products to Seametrics' factory, or another repair facility, as designated by Seametrics.
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- e. Seametrics will deliver repaired products or replacements for defective products to the buyer (ground freight prepaid) to the destination provided in the original order.
- f. Products returned to Seametrics for which Seametrics provides replacement under this warranty shall become the property of Seametrics.
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 - iii. Products not used for their intended purpose
 - iv. Alterations to the product, purposeful or accidental
 - v. Electrical current fluctuations
 - vi. Corrosion due to aggressive materials not approved for your specific product
 - vii. Mishandling, or misapplication of Seametrics products
 - viii. Products or parts that are typically consumed during normal operation
 - ix. Use of parts or supplies (other than those sold by Seametrics) which cause damage to the products, or cause abnormally frequent service calls or service problems
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